# Improving Effectiveness of Simulation Performance Prediction in Clouds

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*Abstract*—The cloud computing is becoming increasingly important execution environment for discrete event simulation models too. The cloud services are expected to provide an automatic and effective parallel and distributed execution but the occurring communication delay in the network may decrease the cloud performance. The paper describes closed queuing network model of on-demand resource use in cloud execution. The paper introduces a method based on coupling factor method and on rough set train-and-test approach of effective simulation performance prediction.

*Keywords*—parallel and distributed simulation, prediction of simulation performance, coupling factor method, cloud execution environment, rough sets, prediction effectiveness

# I. INTRODUCTION AND MOTIVATION

Over the last few years, the need for the discrete event simulation (DES) of large-scale complex networks and network services has been constantly growing because DES turned to be an efficient tool for the analysis of these systems. The computing capacity requirements large-scale and complex networks can be fulfilled by parallel and/or distributed discrete event simulation approach [2, 12,13].

According to a common and simple definition [2], Parallel and Distributed Simulation (PADS) is defined as any simulation in which more than one processor is used. PADS is the execution of a single discrete event simulation model on a high performance computing platform: on clusters of homogeneous and heterogeneous computers, on WEB, grid and *cloud* execution environment.

The typical situations of PADS approach applications from the point of view of the runtime performance requirements: time consuming applications can be for example the simulation of large and/or complex systems and networks.

The development and use of systems based on the PADS methods are resource consuming, not easy task even today. The *simulation performance prediction* method is appropriate for support to reach good PADS performance [11].

The question of support may be formulated in the following way: How to build a model with a good parallelization potential and how to execute it with a good runtime performance involving the necessary (available) resources of a parallel and/or distributed environment and how to do it in an effective way?

The main *contributions* of the paper can be summarized as follows:

- Closed Queuing Network (CQN) Virtual Machine (VM) model of cloud work including modelling of latencies among cloud instances has been defined.
- Closed Queuing Network (CQN) Virtual Machine (VM) model is enhanced to take into account the use of cloud resources (VMs) on on-demand base.
- Rough model of prediction is introduced to support modelling and the performance prediction in an effective way.

The paper is organized as follows. First, the issues of simulation execution in cloud are examined. Then questions of simulation performance are described including the enhanced CQB and VM model of cloud execution. Forth section presents the rough set modelling of performance prediction in an example. The fifth section concludes the work.

# II. ISSUES OF SIMULATION EXECUTION IN CLOUD

# A. Cloud Services

It has four deployment models private cloud, community cloud, public cloud and hybrid cloud.

Cloud services can be provided according to three service models, e.g., Software as a Service (S-a-a-S), Platform as a Service (P-a-a-S) and Infrastructure as a Service (I-a-a-S) [1].

# B. Parallel and Distributed Simulation in the Cloud

Cloud can be the execution environment for PADS with huge capacity requirement since it has made accessible high performance computing platforms (HPC) to end users of the cloud. For example, in the Amazon's very successful Elastic Compute Cloud (EC2), the Message Passing Interface (MPI) – the standard for parallel programming message communications protocol – is supported by the cloud.

Cloud environments are often better at providing high bandwidth communications among applications than in providing *low latency* [15].

PADS applications *typically* work with significant *communication among segments* with sending a lot of short messages between the processes. Thus, for PADS good performance *quick transport (= low latency)* is more important than high bandwidth alone

Problems related with functioning of the cloud, for the PADS applications using *optimistic synchronization* protocol, may lead to performance degradations [16].

There has been made researches in cloud computing and but less attention have been paid to parallel and distributed simulation and even less to *conservative synchronization method*.



Figure 1. CQN switching and latency modell of cloud execution environment (CPU=VM, LP=LP)

### III. SIMULATION PERFORMANCE IN CLOUD

# A. General Model of Cloud Performance Simulation

Buyya define cloud computing in the following way [21]: "A Cloud is a type of parallel and distributed system consisting of a collection of inter-connected and *virtualized* computers that are *dynamically* provisioned and presented as one or more unified computing resource(s) based on service-level agreements established through negotiation between the service provider and consumers."

The principle of locality of execution allows to model the PADS cloud executions as an addition of a stable set and a changing set of processes (Figure 1).

The CQN model with tandems (1, ..., Q) of simple queues (q) for the stable set of processes and ((Q+1),(Q+2), ...) for changing set of processes. Logical process of a tandem is assigned to a virtual machine (VM) Modelling of delay in switching between tandems can be used for modelling the PADS performance (represented by L1 and L2 of dispatching in Figure 1). (The CQN model itself is appropriate for modelling of PADS execution [3,4,9,10,14].)

# B. Latency and Jitter in Cloud

In this point, the network performance of EC2 will be discussed, focusing on the measurements of packet delay measurement in spatial experiment published in [5].

In the experiments in [5], the packet round trip delay (RTT) has been measured in EC2, for 750 small instance pairs and 150 medium instance pairs using 5000 ping probes.

For the examined instance pairs, the measured hop count values were within 4 hops.

Diagram in Figure 2 (that has been built on data measured in [5]), shows the inverse cumulative distribution function (ICDF) of RTTs for small and medium instance pairs.

The diagram shows, that the RTT values among the examined instances are not stable.

Remarks for the min and max RTT values for the small and medium instance pairs:

- the max RTT values for the 95% of small instances are higher than for the medium instances. Range for small instances is are between 4 and 60 msec
- the min RTT values are higher for medium instances (average difference 0,055 msec)

## C. The Coupling Factor Method

The principle of the *Coupling Factor Method (CFM)* of performance prediction [7, 9,17] may be formulated as an inequity:

$$L * E \gg \tau * P$$

where *L* is the lookahead value characterizing the model (simsec), *E* is the event density generated by the model (ev/simsec),  $\tau$  is the latency of messages between logical process (LPs) of the model (sec), and *P* is the event processing computation hardware performance (ev/sec).

According to the method, the coupling factor  $\lambda$  is calculated according to the formulas

$$\lambda = \frac{L * E}{\tau * P}$$

The high value of the coupling factor  $\lambda$  shows the good potential of the simulation model for parallelization. The formula involves only four parameters for the calculation which can be measured in simple sequential simulation runs.

For a separate process, the  $\lambda_N$  parallelization potential of a process is only a part of the whole potential:

$$\lambda_N = \frac{L * E}{\tau * P} * \frac{1}{N_{LP}}$$

where  $N_{LP}$  the number of the LPs [8].

## D. Setting up the Scale Prediction for a Homogeneous Cluster

For the presented method, the results described in [8] will be used in the cloud performance analysis.

The hardware environment is a *homogeneous cluster* of 12 PCs. For the experiments in the case, the starting number of jobs is 2 jobs/simple queue with exponential interarrival time and with exponential service time distributions (the expected value for arrival and service time is 10sec). The delay on links between simple queues is 1sec. The number of tandem queues is 24 (Q), the number of simple queues/tandem queue is 50 (q). The switching in CQN model is performed by uniform distribution to switch to the next tandem queue, and the delay of switching models lookahead.



Figure 1. ICDF of max and min RTTs for small and medium sized instances in EC

The task assignment principles in the execution are the partitioning into LPs and Load Balancing Criterion.

COUPLING FACTOR MEASUREMENT AND CALCULATION

TABLE I.

0.1 [sims [ev] Number of 3. WCT (N=1) [sec] Р [ev/sec] F 0.000025 0.000025 0.00002 0.000025 [sec] R=P/F L/τ 2.43 24.1 

TABLE II. Coupling Factor Measurement and Calculation

sequential simulation runs are summarized in Table I.

The measured value of  $\tau$  is 0,025ms for the system in the case. The value of variables that have been measured in

	1.		RTT(ms)	latency(ms)	T latency	proportion	λ shift (log10)
	2.	CQN model T		0,025			
	3.	EC2 average	0,2	0,1	4		0,60
	4.	EC2 average	3	0,15	4,2		0,62
	5.	EC2 small instances	10	5	200	55%	
	6.	EC2 medium instances	20	10	400	20%	
	7.	EC2 small instances weighted r latency		2,84	113,6		2,06
	8.	EC2 medium instances weighted t latency		2,16	86,4		1,94

# E. Analysis

Table II summarizes the EC2 latency measurements [5] and the calculated  $\lambda$  shifts in predicted relative speedup [19].

#### IV. EXAMPLE OF ROUGH SET MODEL OF CLOUD EXECUTION

The RST model of simulation performance prediction can be set up in the form of decision information system (DIS) and decision tables:

 $I = (U, C \cup D, f_{V'}, f, V', V)$ , (before discretization and coding)

 $I = (U, A = C \cup D, f, V),$ 

 $I = (U, A = C \cup \{d\}, f, V), d \in D$ .

The simulation experiments (sequential and PADS runs) will be the *objects* of the universe

 $U = \{x_1, x_2, x_3, \dots, x_{|U|}\}$ 

where  $x_i$  denotes the *i*-th simulation experiment of the universe.

The set of condition attributes may be defined as follows

$$C_{Cloud \ CFM \ model \ hardware - software \ features} = \{P, E, L1, L2, \lambda, \lambda_N, N_{LP}, \tau(RTT / 2), N_{VMs}$$
  
simulated time, runtime (wall - clock time)}  $\cup$ 

Chardware-software environment { OMNet +

 $+, MPI, Linux Debian \} \cup$ 

 $C_{Cloud CON models' features}$ 

(conservative synchronisation protocol U

with null message algorithm

{ Q, q, propagation delay between simple queues, switching time between tandems,

starting number of jobs of simple queues in cloud CQN models,

inter arrival time of jobs,

service time, service discipline (FCFS) }

In set *C*, attributes, relating to the coupling factor method, are in accordance with the homogeneous execution environment and with the equal (fair load balancing criterion too (implicit) condition attributes)

The set of *decision* attributes under consideration can be set as

speedup, R - speedup, $D = \begin{cases} spectrup, n & operation \\ number of vacationing jobs in L1 and L2 \end{cases}$ 

The RST exploring of the coupling factor method is following decision performed using the table: discretization and coding

 $I_t = (U, A = C \cup \{d_t\}, f, V), d_t \in D,$ 

The examination is executed in a form of a train-andtest analysis:

 $U \rightarrow (U_{training(i)}, U_{test(i)})(i = 1, 2, 3, \dots, |steps|),$ 

 $f_{RNDsplit(U,i)}: U \rightarrow (U_{training}, U_{test})$  with

 $\forall (i)(i = 1, 2, \dots) (U_{training(i)} \cup U_{test(i)} = U) \land$  $\left( \left| U_{training(i)} \right| / \left| U_{test(i)} \right| = \frac{x}{\gamma} \right) \land (RND_{seed} = i).$ 

For the train-and-test examination, the ROSETTA system [18] can be used with some selected rule generation algorithm G (for example, Johnson's RSES (Rough Set Exploration System)) and with the subsequent classification of objects.

For evaluation purposes, re-classification rules  $S_{self-training(i)}$  can be generated for every  $U_{test(i)}$  using the same rule generation and classification algorithm.

For the efficacy, efficiency and effectiveness analysis, [20] the simulation cost K[sec] expressed in computing time "consumption" should also be calculated, including cost of attributes, rules, simulation experiments and predictions, for the series of predictions  $(K(S_{training(i)}), K(S_{training(i)}))$ i = 1, 2, 3, ..., |steps = number of predictions|)

This analysis provides a feedback to the simulation model and to the the simulation performance model too, supporting model features identification and refinement.

#### CONCLUSION V.

In the paper, a model of cloud execution has been described which models the network latencies

This is a Closed Queuing Network (CQN) and Virtual Machine (VM) model of cloud work modelling network latencies among cloud instances

In the paper, the CQN and VM model has been extended in to take into account the on-demand base use of cloud resources

In an example, a rough model of prediction is introduced to support effective modelling and performance prediction

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LÁSZLÓ MUKA graduated in electrical engineering at the Technical University of Lvov in 1976. He got his special engineering degree in digital electronics at the Technical University of Budapest in 1981, and became a university doctor in architectures of CAD systems in 1987. Mr. Muka finished an MBA at Brunel University of London in 1996. Since 1996 he has been working in the area of modeling and simulation of infocommunications systems, including human subsystems. Mr. Muka got his PhD at the Budapest University of Technology and Economics in 2011. Dr. Muka has been working as an Associate Professor for the Széchenyi István University in Győr since the February of 2012. He teaches system simulation and network security

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